# Abstraction-Based Segmental Simulation of Chemical Reaction Networks

Computational Methods in Systems Biology (CMSB 2022)

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- Idea: using memorization

#### **Example: Viral Infection**

Species	RNA, DNA, V, P
Initial state	(1  imes RNA)
End time	200s
Reactions	$DNA + P \xrightarrow{0.00001125 \cdot DNA \cdot P} V$
	$RNA \xrightarrow{1000 \cdot RNA} RNA + P$
	$DNA \xrightarrow{0.025 \cdot DNA} DNA + RNA$
	$RNA \xrightarrow{1 \cdot RNA} DNA + RNA$
	$RNA \xrightarrow{0.25 \cdot RNA} \emptyset$
	$P \xrightarrow{1.9985 \cdot P} \emptyset$

- Evolution governed by Chemical Master Equation
- Gives rise to discrete-space continuous-time Markov chain (CTMC)

#### Gillespie's stochastic simulation algorithm (SSA) [3]

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$$t = 0s$$
 •  $S_{init}$ 

Start in initial state.

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Compute rate of all reactions according to their propensity functions.

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Time until the next reaction:  $\Delta t \sim EXP(0.5+2+1.5)$ Probability of reactions:  $\frac{0.5}{4}, \frac{2}{4}, \frac{1.5}{4}$ 

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#### Gillespie's stochastic simulation algorithm (SSA) [3]

Sample one reaction at a time



Time until the next reaction:  $\Delta t \sim EXP(4+2+3+1)$ Probability of reactions:  $\frac{4}{10}, \frac{2}{10}, \frac{3}{10}, \frac{1}{10}$ 

#### Gillespie's stochastic simulation algorithm (SSA) [3]

- Sample one reaction at a time
- May take a long time



Precompute k short trajectories (called segments) for each state.  $\rightarrow$  Simulate by sampling segments instead of single reactions.



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- Problem: many states  $\rightarrow$  too inefficient

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- Population levels grow exponentially
- Choose representative for each abstract state (usually center)

Only precompute k segments for each representative.



Segments end when they leave the abstract state.

```
\rightarrow Intuition: "significant change"
```

















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To save memory: Work with summaries instead of segments.



Lazy: Do not precompute but fill memory on-the-fly!



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- 1. Limited number of memorized segments:
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  - Error vanishes for  $k \to \infty$
- 2. Using representative's segments
  - Similar species counts  $\rightarrow$  similar propensities  $\rightarrow$  similar segments
  - Error gets smaller if we add more population levels

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SSA - Simulation 1



SSA - Simulation 2



SSA - Simulation 3



SEG - Simulation 4



SEG - Simulation 5



SEG - Simulation 6





	Mean	Var
SSA	13.6	2878
SEG	13.5	2685





#### Speed-up:



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- Accelerates with number of simulations
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- Memorization: trade-off between speed and memory

#### Oversimplified comparison with other approaches:

Approach	Speed-up	Accuracy
SSA [3]	1x	perfect
au-leaping [2]	$\sim$ 5x	very good
Hybrid Simulation [4]	$\sim$ 50x	good
Deep Learning <sup>1</sup> [1]	$\sim$ 100×	good
Segmental Simulation <sup>2</sup>	$\sim$ 200x	good

<sup>&</sup>lt;sup>1</sup>requires precomputed data and long training period

<sup>&</sup>lt;sup>2</sup>significant memory requirement

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Species	ON, OFF, X
Initial state	$(1 \times ON, 50 \times X)$
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	$OFF \rightarrow ON + X$

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## Lazy Algorithm

```
Inputs : \mathcal{N} (CRN), k (number of segments), c (partitioning parameter),
            t_{end} (time horizon), s_{init} (initial state) and m (number of simulations)
   Output: list of m segmental simulations
1 simulations := [];
2 memory := \{\};
                                   // mapping each abstract state to a list of segments
3 for 1 to m do
        s := s_{init}; t := 0; simulation := [(s, t)];
 4
       while t < t_{end} do
 5
             a := abstractState<sub>c</sub>(s);
6
             if |memory(a)| < k then
7
                 segment := sampleNewSegm(N, a.representative); // sample new segment
8
                 memory(a).add(segment);
9
                                                                         // save it for reuse
             else
10
                 segment := chooseUniformlyFrom(memory(a));
                                                                        // reuse old segment
11
             end
12
             // apply segment's relative effects
             s := s + segment.\Delta_{state}; t := t + segment.\Delta_{time};
13
             simulation.add((s, t));
14
       end
15
        simulations.add(simulation);
16
17 end
18 return simulations
```
Mod.	SSA	SEG <i>k</i> =10			SEG k=100			SEG k=1000		
		<i>c</i> =2	c = 1.5	c=1.3	<i>c</i> =2	c=1.5	c=1.3	<i>c</i> =2	c=1.5	c=1.3
PP	0.014s	70×	70×	70x	70×	70×	23x	28x	23x	12x
VI	0.88s	730x	380x	180x	100×	48x	17x	8.6x	4.8x	2.9x
TS	22s	360x	360x	340×	390x	350x	280x	250x	190×	110x
RP	9.1s	760×	540x	320x	300x	140x	62x	54x	21x	7.4x

**Table 1:** Average run-time of one SSA simulation and the speedup factor of segmental simulation when computing 10,000 simulations with different abstraction parameters.

Mod.	SEG <i>k</i> =10			SI	EG $k=1$	00	SEG k=1000		
	<i>c</i> =2	c=1.5	c=1.3	<i>c</i> =2	c=1.5	c=1.3	<i>c</i> =2	c=1.5	c=1.3
PP	25kb	61kb	130kb	250kb	570kb	1.3mb	2.2mb	4.8mb	11mb
VI	210kb	730kb	2.0mb	1.8mb	4.8mb	13mb	11mb	25mb	53mb
TS	1.2mb	3.0mb	8.7mb	15mb	37mb	85mb	100mb	250mb	550mb
RP	3.8mb	12mb	34mb	43mb	120mb	300mb	310mb	760mb	1.0gb

 Table 2: Size of segmental abstraction after 10,000 simulations for different parameters.